



## CAYLEY GRAPHS UNDER GRAPH OPERATIONS II

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**ABSTRACT.** The aim of this paper is to investigate the behavior of Cayley graphs under some graph operations. It is proved that the *NEPS*, corona, hierarchical, strong, skew and converse skew products of Cayley graphs are again Cayley graphs under some conditions.

### 1. INTRODUCTION AND PRELIMINARIES

All groups considered here are finite. For notation and definitions not defined here we refer the reader to [4, 5]. Let  $X$  and  $Y$  be two graphs. Their corona of  $X$  and  $Y$ ,  $X \circ Y$ , is defined as the graph obtained by taking one copy of  $X$  and joining the  $i$ -th vertex of  $X$  to every vertex in  $i$ -th copy of  $Y$ . Following Petrović [7], we assume that  $\Gamma_i = (X_i, U_i)$ ,  $1 \leq i \leq n$  are finite graphs, where  $X_i$  and  $U_i$  denote the corresponding sets of vertices and of edges. Further, let  $\beta$  be a set of  $n$ -tuples  $(\beta_1, \dots, \beta_n)$  of symbols 0 and 1, which does not contain the  $n$ -tuple  $(0, \dots, 0)$ . The NEPS with basis  $\beta$  of the graphs  $G_1, \dots, G_n$  is the graph  $Z = (X, U)$ , where  $X = X_1 \times \dots \times X_n$  and in which two vertices  $(x_1, \dots, x_n)$  and  $(y_1, \dots, y_n)$  are adjacent if and only if there is an  $n$ -tuple  $(\beta_1, \dots, \beta_n)$  in  $\beta$  such that  $x_i = y_i$  holds exactly when  $\beta_i = 0$ , and  $x_i$  is adjacent to  $y_i$  in  $\Gamma_i$ , exactly when  $\beta_i = 1$ . It is easy to see that Cartesian product, tensor product and strong product of graphs are special types of NEPS.

The Strong product  $X \boxtimes Y$  of graphs  $X$  and  $Y$  has the vertex set  $V(X \boxtimes Y) = V(X) \times V(Y)$  and  $(a, x)(b, y)$  is an edge of  $X \boxtimes Y$  if  $a = b$  and  $xy \in E(Y)$ , or  $ab \in E(X)$  and  $x = y$ , or  $ab \in E(X)$  and  $xy \in E(Y)$ .

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Let  $G_i = (V_i, E_i)$  be  $N$  graphs with each vertex set  $V_i$ ,  $1 \leq i \leq N$ , having a distinguished or root vertex, labeled 0. The hierarchical product [3]  $H = G_N \square \cdots \square G_2 \square G_1$  is the graph with vertices the  $N$ -tuples  $x_N \cdots x_3 x_2 x_1$ ,  $x_i \in V_i$ , and edges defined by the following adjacencies:

$$x_N \cdots x_3 x_2 x_1 \sim \begin{cases} x_N \cdots x_3 x_2 x_1 & \text{if } y_1 \sim x_1 \text{ in } G_1, \\ x_N \cdots x_3 y_2 x_1 & \text{if } y_2 \sim x_2 \text{ in } G_2 \text{ and } x_1 = 0, \\ x_N \cdots y_3 x_2 x_1 & \text{if } y_3 \sim x_3 \text{ in } G_3 \text{ and } x_1 = x_2 = 0, \\ \vdots & \vdots \\ y_N \cdots x_3 x_2 x_1 & \text{if } y_N \sim x_N \text{ in } G_N \text{ and } x_1 = x_2 = \cdots = x_N = 0. \end{cases}$$

We encourage the interested readers to consult papers [2] for a generalization and more information on this topic.

We now define the skew product and converse skew product of two graphs  $G_1$  and  $G_2$  denoted by  $G_1 \Delta G_2$  and  $G_1 \nabla G_2$ , respectively. These graph products are having  $V(G_1) \times V(G_2)$  as their vertex set. The edge sets of these graphs are:

$$\begin{aligned} E(G_1 \Delta G_2) &= \{(u_1, u_2)(v_1, v_2) \mid [u_1 = v_1 \text{ and } u_2 v_2 \in E(G_2)] \text{ or } [u_1 v_1 \in E(G_1) \text{ and } u_2 v_2 \in E(G_2)]\}, \\ E(G_1 \nabla G_2) &= \{(u_1, u_2)(v_1, v_2) \mid [u_2 = v_2 \text{ and } u_1 v_1 \in E(G_1)] \text{ or } [u_1 v_1 \in E(G_1) \text{ and } u_2 v_2 \in E(G_2)]\}, \end{aligned}$$

see [8] for details.

Suppose  $G_1$  and  $G_2$  are two arbitrary graphs. The cluster  $G_1\{G_2\}$ , is obtained by taking one copy of  $G_1$  and  $|G_1|$  copies of a rooted graph  $G_2$ , and by identifying the root of the  $i$ -th copy of  $G_2$  with the  $i$ -th vertex of  $G_1$ ,  $1 \leq i \leq |G_1|$ . The cluster of graphs was introduced by Yeh and Gutman [9] in the context of distance in graphs.

The Cartesian product  $G_1 \square G_2$  is graph with  $V(G_1) \times V(G_2)$  as vertex set such that  $(a, x)$  and  $(b, y)$  are adjacent if and only if  $a = b$  and  $xy \in E_2$ , or  $ab \in E_1$  and  $x = y$ .

Baik et al. [1, Lemma 2.6], proved that if  $G = G_1 \times G_2$  are the direct product of two finite groups  $G_1, G_2$  and  $S_1$  and  $S_2$  are subsets of  $G_1$  and  $G_2$ , respectively, then by choosing  $S$  to be the disjoint union of  $S_1$  and  $S_2$ , we have  $Cay(G, S) \cong Cay(G_1, S_1) \square Cay(G_2, S_2)$ . The aim of this paper is to extend this result to corona, hierarchical product, skew product, converse skew product and NEPS of graphs. We refer to [1, 6] for more study on the main problem of this paper.

## 2. MAIN RESULTS

The investigation of graph operations under graph invariants is a well-known problem in metric graph theory. Here, we are interested to algebraic invariants. We begin by considering corona of two graphs.

**Proposition 2.1.** *Suppose  $\Gamma_1 = Cay(G_1, S_1)$ ,  $\Gamma_2 = Cay(G_2, S_2)$  and  $\Gamma = Cay(G, S)$ , where  $G$  is a group of order  $|G_1| \cdot |G_2| + |G_1|$  and  $S \subseteq G$ . Then  $\Gamma = \Gamma_1 \circ \Gamma_2$  if and only if  $\Gamma_1$  is empty,  $\Gamma_2$  is a complete graph and  $\Gamma$  is a disconnected graph with  $|G_1|$  components that each of them are regular of degree  $|G_2|$ .*

*Proof.* We first assume that  $\Gamma = \Gamma_1 \circ \Gamma_2$ . Choose vertices  $u, v \in V(\Gamma)$  such that  $u \in V(\Gamma_1)$  and  $v$  is vertex of the  $i$ -th copy of  $\Gamma_2$ . Then  $deg_{\Gamma_1}(u) + |V(\Gamma_2)| =$

$\deg_{\Gamma_2}(v) + 1$ . Since  $|V(\Gamma_2)| \geq \deg_{\Gamma_2}(v) + 1$ ,  $\deg_{\Gamma_1}(u) = 0$ . This implies that  $\Gamma_1$  is empty,  $\Gamma_2$  is complete and  $\Gamma_1 \circ \Gamma_2$  is a disconnected graph with  $G_1$  components that each of them are regular of degree  $|G_2|$ , as desired. The converse is obvious.  $\square$

**Proposition 2.2.** *Suppose  $G$  is a group,  $G_1$  and  $G_2$  are subgroups of  $G$ ,  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\Gamma = \text{Cay}(G, S_1)$  and  $G = G_2 \cdot G_1 = \{xy \mid x \in G_2 \ \& \ y \in G_1\}$ . Then  $\Gamma = \Gamma_2 \sqcap \Gamma_1$  if and only if  $\Gamma_2$  is empty.*

*Proof.* We first assume that  $\Gamma = \Gamma_2 \sqcap \Gamma_1$ . Choose vertices  $x_20, x_2x_1 \in \Gamma$ . Since  $\deg_{\Gamma_2 \sqcap \Gamma_1}(x_2x_1) = \deg_{\Gamma_2 \sqcap \Gamma_1}(x_20)$ ,  $\deg_{\Gamma_1}(x_1) = \deg_{\Gamma_2}(x_2) + \deg_{\Gamma_1}(0)$ . This shows that  $\deg_{\Gamma_2}(x_2) = 0$ , which implies that  $\Gamma_2$  is empty. The converse is a direct consequence of the definition.  $\square$

**Corollary 2.3.** *Let  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\dots$ ,  $\Gamma_n = \text{Cay}(G_n, S_n)$  and  $\Gamma = \text{Cay}(G, S_1)$ , where  $G = G_n G_{n-1} \cdots G_1$ . Then  $\Gamma = \Gamma_n \sqcap \Gamma_{n-1} \sqcap \cdots \sqcap \Gamma_1$  if and only if  $\Gamma_2, \dots, \Gamma_n$  are empty graphs.*

**Proposition 2.4.** *Suppose  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $r$  is a root vertex of  $\Gamma_2$ ,  $G = G_1 \times G_2$ ,  $S = \{(e, x) \mid x \in S_2\}$  and  $\Gamma = \text{Cay}(G, S)$ . Then  $\Gamma_1 \{ \Gamma_2 \} \cong \Gamma$  if and only if  $\Gamma_1$  is empty.*

*Proof.* We first assume that  $\Gamma_1 \{ \Gamma_2 \} \cong \Gamma$ . Then  $\Gamma_1 \{ \Gamma_2 \}$  is a  $|S|$ -regular graph. Suppose  $u \in G_1$  and  $v \in G_2$ . Then  $\deg_{\Gamma_1}(u) + \deg_{\Gamma_2}(r) = \deg_{\Gamma_2}(v)$ . Since  $\Gamma_2$  is regular,  $\deg_{\Gamma_1}(u) = 0$ . So,  $\Gamma_1$  is empty. The converse is a direct consequence of the definition.  $\square$

**Proposition 2.5.** *Let  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\overline{S_1} = \{(e, y) \mid y \in S_2\}$ ,  $\overline{S_2} = \{(t, z) \mid t \in S_1, z \in S_2\}$  and  $\Gamma = \text{Cay}(G, S)$ , where  $G = G_1 \times G_2$ .  $\hat{A}\check{N}$ If  $S = \overline{S_1} \cup \overline{S_2}$  then  $\Gamma = \Gamma_1 \Delta \Gamma_2$ .*

*Proof.* By the definition,  $V(\Gamma) = V(\Gamma_1 \Delta \Gamma_2) = V(\Gamma_1) \times V(\Gamma_2)$ , as desired. On the other hand,

$$\begin{aligned} E(\Gamma) &= \left\{ (a, b)(c, d) \mid (a, b)(c^{-1}, d^{-1}) \in S \right\} \\ &= \left\{ (a, b)(c, d) \mid (ac^{-1}, bd^{-1}) \in S \right\} \\ &= \left\{ (a, b)(c, d) \mid (ac^{-1}, bd^{-1}) \in \overline{S_1} \vee (ac^{-1}, bd^{-1}) \in \overline{S_2} \right\} \\ &= \left\{ (a, b)(c, d) \mid (ac^{-1} = e \wedge bd^{-1} \in S_2) \vee (ac^{-1} \in S_1 \wedge bd^{-1} \in S_2) \right\} \\ &= \left\{ (a, b)(c, d) \mid (a = c \wedge bd \in E(\Gamma_2)) \vee (ac \in E(\Gamma_1) \wedge bd \in E(\Gamma_2)) \right\} \\ &= E(\Gamma_1 \Delta \Gamma_2) \end{aligned}$$

Therefore,  $\Gamma = \Gamma_1 \Delta \Gamma_2$ , which completes our argument.  $\square$

Notice that the set  $S$  in Proposition 2.5, is not necessarily unique. To do this, we find another set  $S'$  such that  $\text{Cay}(G, S) \cong \text{Cay}(G, S') \cong \Gamma_1 \Delta \Gamma_2$ . To do this, it is enough to consider the Cayley graphs

$$\text{Cay}\left(V_4 \times \mathbb{Z}_2, \{(a, 0), (c, 1), (b, 0)\}\right),$$

$$\text{Cay}(V_4, \{a, b\}) \triangle \text{Cay}(\mathbb{Z}_2, \{1\}),$$

and notice that they are isomorphic graphs and

$$\{(a, 1), (b, 1), (e, 1)\} \neq \{(a, 0), (c, 1), (b, 0)\}.$$

**Corollary 2.6.** *Let  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\dots$ ,  $\Gamma_n = \text{Cay}(G_n, S_n)$  and  $\Gamma = \text{Cay}(G, S)$ , where  $G = G_1 \times G_2 \times \dots \times G_n$ . Define:*

$$\begin{aligned} \overline{S_i} &= \{(e, e, \dots, e, x_i, x_{i+1}, \dots, x_n) \mid x_j \in S_j; i \leq j \leq n\}, \quad 1 \leq i \leq n, \\ S &= \overline{S_1} \cup \overline{S_2} \cup \dots \cup \overline{S_n}. \end{aligned}$$

Then,

$$\Gamma = \left( \dots \left( (\Gamma_1 \triangle \Gamma_2) \triangle \Gamma_3 \right) \triangle \dots \right) \triangle \Gamma_n.$$

*Proof.* By the definition,  $V(\Gamma) = V\left(\left(\dots\left((\Gamma_1 \triangle \Gamma_2) \triangle \Gamma_3\right) \triangle \dots\right) \triangle \Gamma_n\right) = V(\Gamma_1) \times \dots \times V(\Gamma_n)$ . On the other hand,

$$\begin{aligned} E(\Gamma) &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1b_1^{-1}, a_2b_2^{-1}, \dots, a_nb_n^{-1}) \in S \right\} \\ &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1b_1^{-1}, a_2b_2^{-1}, \dots, a_nb_n^{-1}) \in \overline{S_1} \right. \\ &\quad \left. \vee (a_1b_1^{-1}, a_2b_2^{-1}, \dots, a_nb_n^{-1}) \in \overline{S_2} \vee \dots \vee (a_1b_1^{-1}, a_2b_2^{-1}, \dots, a_nb_n^{-1}) \in \overline{S_n} \right\} \\ &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1b_1^{-1} \in S_1, a_2b_2^{-1} \in S_2, \dots, a_nb_n^{-1} \in S_n) \right. \\ &\quad \left. \vee (a_1b_1^{-1} = e, a_2b_2^{-1} \in S_2, \dots, a_nb_n^{-1} \in S_n) \right. \\ &\quad \left. \vee (a_1b_1^{-1} = e, a_2b_2^{-1} = e, a_3b_3^{-1} \in S_3, \dots, a_nb_n^{-1} \in S_n) \right. \\ &\quad \left. \vee \dots \vee (a_1b_1^{-1} = e, \dots, a_{n-1}b_{n-1}^{-1} = e, a_nb_n^{-1} \in S_n) \right\} \\ &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid \left( \left( (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2)) \right. \right. \right. \\ &\quad \left. \left. \vee (a_1 = b_1 \wedge a_2b_2 \in E(\Gamma_2)) \right) \wedge (a_3b_3 \in E(\Gamma_3) \wedge \dots \wedge a_nb_n \in E(\Gamma_n)) \right) \\ &\quad \vee (a_1 = b_1 \wedge a_2 = b_2 \wedge a_3b_3 \in E(\Gamma_3) \wedge \dots \wedge a_nb_n \in E(\Gamma_n)) \\ &\quad \left. \vee \dots \vee (a_1 = b_1 \wedge a_2 = b_2 \wedge \dots \wedge a_{n-1} = b_{n-1} \wedge a_nb_n \in E(\Gamma_n)) \right\} \\ &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid \left( \left( ((a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \triangle \Gamma_2) \right. \right. \right. \\ &\quad \left. \left. \wedge a_3b_3 \in E(\Gamma_3) \right) \vee (a_1 = b_1 \wedge a_2 = b_2 \wedge a_3b_3 \in E(\Gamma_3)) \right) \\ &\quad \left. \wedge (a_4 = b_4 \wedge \dots \wedge a_{n-1} = b_{n-1} \wedge a_nb_n \in E(\Gamma_n)) \right) \\ &\quad \left. \vee \dots \vee (a_1 = b_1 \wedge a_2 = b_2 \wedge \dots \wedge a_{n-1} = b_{n-1} \wedge a_nb_n \in E(\Gamma_n)) \right\}. \end{aligned}$$

So,

$$\begin{aligned}
 E(\Gamma) &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid \left( \left( (a_1, a_2, a_3)(b_1, b_2, b_3) \in E((\Gamma_1 \Delta \Gamma_2) \Delta \Gamma_3) \right. \right. \right. \\
 &\wedge a_4 b_4 \in E(\Gamma_4) \Big) \vee (a_1 = b_1 \wedge a_2 = b_2 \wedge a_3 = b_3 \wedge a_4 b_4 \in E(\Gamma_4)) \Big) \\
 &\wedge (a_5 b_5 \in E(\Gamma_5) \wedge \dots \wedge a_n b_n \in E(\Gamma_n)) \Big) \\
 &\vee \dots \vee (a_1 = b_1 \wedge a_2 = b_2 \wedge \dots \wedge a_{n-1} = b_{n-1} \wedge a_n b_n \in E(\Gamma_n)) \Big\} \\
 &= \dots
 \end{aligned}$$

Therefore,

$$\begin{aligned}
 E(\Gamma) &= \left\{ (a_1, \dots, a_n)(b_1, \dots, b_n) \mid \left( (a_1, \dots, a_{n-1})(b_1, \dots, b_{n-1}) \right. \right. \\
 &\in E \left( \left( \dots \left( (\Gamma_1 \Delta \Gamma_2) \Delta \Gamma_3 \right) \Delta \dots \Delta \Gamma_{n-1} \right) \right) \wedge a_n b_n \in E(\Gamma_n) \Big) \\
 &\vee \left( (a_1 = b_1 \wedge a_2 = b_2 \wedge \dots \wedge a_{n-1} = b_{n-1} \wedge a_n b_n \in E(\Gamma_n)) \right) \Big\} \\
 &= E \left( \left( \dots \left( (\Gamma_1 \Delta \Gamma_2) \Delta \Gamma_3 \right) \Delta \dots \Delta \Gamma_n \right) \right),
 \end{aligned}$$

which implies that  $\Gamma = \left( \dots \left( (\Gamma_1 \Delta \Gamma_2) \Delta \Gamma_3 \right) \Delta \dots \right) \Delta \Gamma_n$ .  $\square$

We can define the skew product of  $n$  graphs  $\Gamma_1, \Gamma_2, \dots, \Gamma_n$  by

$$\Gamma_1 \Delta \left( \Gamma_2 \Delta \left( \Gamma_3 \Delta \left( \dots \Delta \left( \Gamma_{n-1} \Delta \Gamma_n \right) \dots \right) \right) \right).$$

Then the vertex set will be again  $V(\Gamma_1) \times \dots \times V(\Gamma_n)$  and two vertices

$$(x_1, x_2, \dots, x_n) \text{ and } (y_1, y_2, \dots, y_n)$$

are adjacent if and only if  $x_n y_n \in E(\Gamma_n)$  and for each  $j$ ,  $1 \leq j \leq n-1$ ,  $x_j = y_j$  or  $x_j y_j \in E(\Gamma_j)$ .

**Corollary 2.7.** *Let  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\dots$ ,  $\Gamma_n = \text{Cay}(G_n, S_n)$  and  $\Gamma = \text{Cay}(G, S)$ , where  $G = G_1 \times G_2 \times \dots \times G_n$  and  $S = \{(x_1, x_2, \dots, x_n) \mid \forall 1 \leq j \leq n-1 : x_j \in S_j \vee x_j = e, x_n \in S_n\}$ . Then*

$$\Gamma = \Gamma_1 \Delta \left( \Gamma_2 \Delta \left( \Gamma_3 \Delta \left( \dots \Delta \left( \Gamma_{n-1} \Delta \Gamma_n \right) \dots \right) \right) \right).$$

*Proof.* We will present the proof for  $n = 4$ . The proof in general is similar, but lengthy. We first notice that  $V(\Gamma) = V(\Gamma_1 \Delta (\Gamma_2 \Delta (\Gamma_3 \Delta \Gamma_4))) = V(\Gamma_1) \times V(\Gamma_2) \times V(\Gamma_3) \times V(\Gamma_4)$ . So, it is enough to prove the equality of edge sets.

$$\begin{aligned}
E(\Gamma) &= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid (a_1b_1^{-1}, a_2b_2^{-1}, a_3b_3^{-1}, a_4b_4^{-1}) \in S \right\} \\
&= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid (a_1b_1^{-1} = e \wedge a_2b_2^{-1} = e \wedge a_3b_3^{-1} = e \right. \\
&\quad \wedge a_4b_4^{-1} \in S_4) \\
&\quad \vee (a_1b_1^{-1} = e \wedge a_2b_2^{-1} = e \wedge a_3b_3^{-1} \in S_3 \wedge a_4b_4^{-1} \in S_4) \\
&\quad \vee (a_1b_1^{-1} = e \wedge a_2b_2^{-1} \in S_2 \wedge a_3b_3^{-1} \in S_3 \wedge a_4b_4^{-1} \in S_4) \\
&\quad \vee (a_1b_1^{-1} = e \wedge a_2b_2^{-1} \in S_2 \wedge a_3b_3^{-1} = e \wedge a_4b_4^{-1} \in S_4) \\
&\quad \vee (a_1b_1^{-1} \in S_1 \wedge a_2b_2^{-1} \in S_2 \wedge a_3b_3^{-1} \in S_3 \wedge a_4b_4^{-1} \in S_4) \\
&\quad \vee (a_1b_1^{-1} \in S_1 \wedge a_2b_2^{-1} \in S_2 \wedge a_3b_3^{-1} = e \wedge a_4b_4^{-1} \in S_4) \\
&\quad \vee (a_1b_1^{-1} \in S_1 \wedge a_2b_2^{-1} = e \wedge a_3b_3^{-1} = e \wedge a_4b_4^{-1} \in S_4) \\
&\quad \left. \vee (a_1b_1^{-1} \in S_1 \wedge a_2b_2^{-1} = e \wedge a_3b_3^{-1} \in S_3 \wedge a_4b_4^{-1} \in S_4) \right\} \\
&= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid (a_1 = b_1 \wedge a_2 = b_2 \wedge a_3 = b_3 \right. \\
&\quad \wedge a_4b_4 \in E(\Gamma_4)) \vee (a_1 = b_1 \wedge a_2 = b_2 \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee (a_1 = b_1 \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee (a_1 = b_1 \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \left. \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \right\} \\
&= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \left( (a_1 = b_1 \wedge a_2 = b_2) \right. \right. \\
&\quad \wedge \left. \left( (a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \vee (a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \right) \right) \\
&\quad \vee \left( (a_1 = b_1 \wedge a_2b_2 \in E(\Gamma_2)) \wedge \left( (a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \right. \right. \\
&\quad \left. \left. \vee (a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \right) \right) \vee \left( (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2)) \right. \\
&\quad \wedge \left. \left( (a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \vee (a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \right) \right) \\
&\quad \vee \left( (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2) \wedge \left( (a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \right. \right. \\
&\quad \left. \left. \vee (a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \right) \right) \left. \right\}.
\end{aligned}$$

Therefore,

$$\begin{aligned}
 E(\Gamma) &= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \right. \\
 &\quad \left( (a_1 = b_1 \wedge a_2 = b_2) \wedge (a_3, a_4)(b_3, b_4) \in E(\Gamma_3 \Delta \Gamma_4) \right) \\
 &\vee \left( (a_1 = b_1 \wedge a_2 b_2 \in E(\Gamma_2)) \wedge (a_3, a_4)(b_3, b_4) \in E(\Gamma_3 \Delta \Gamma_4) \right) \\
 &\vee \left( (a_1 b_1 \in E(\Gamma_1) \wedge a_2 b_2 \in E(\Gamma_2)) \wedge (a_3, a_4)(b_3, b_4) \in E(\Gamma_3 \Delta \Gamma_4) \right) \\
 &\vee \left. \left( (a_1 b_1 \in E(\Gamma_1) \wedge a_2 = b_2) \wedge (a_3, a_4)(b_3, b_4) \in E(\Gamma_3 \Delta \Gamma_4) \right) \right\} \\
 &= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \left( a_1 = b_1 \wedge \left( (a_2 = b_2 \wedge (a_3, a_4)(b_3, b_4) \right) \right) \right. \right. \\
 &\quad \left. \left. \in E(\Gamma_3 \Delta \Gamma_4) \right) \vee \left( a_2 b_2 \in E(\Gamma_2) \wedge (a_3, a_4)(b_3, b_4) \in E(\Gamma_3 \Delta \Gamma_4) \right) \right\} \\
 &\vee \left( a_1 b_1 \in E(\Gamma_1) \wedge \left( (a_2 b_2 \in E(\Gamma_2) \wedge (a_3, a_4)(b_3, b_4) \in E(\Gamma_3 \Delta \Gamma_4)) \right) \right) \\
 &\vee \left. \left( a_2 = b_2 \wedge (a_3, a_4)(b_3, b_4) \in E(\Gamma_3 \Delta \Gamma_4) \right) \right\} \\
 &= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \right. \\
 &\quad \left( a_1 = b_1 \wedge (a_1, a_2, a_3)(b_1, b_2, b_3) \in E(\Gamma_2 \Delta (\Gamma_3 \Delta \Gamma_4)) \right) \\
 &\vee \left. \left( a_1 b_1 \in E(\Gamma_1) \wedge (a_1, a_2, a_3)(b_1, b_2, b_3) \in E(\Gamma_2 \Delta (\Gamma_3 \Delta \Gamma_4)) \right) \right\} \\
 &= E(\Gamma_1 \Delta (\Gamma_2 \Delta (\Gamma_3 \Delta \Gamma_4))).
 \end{aligned}$$

□

**Proposition 2.8.** *Suppose that  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\overline{S_1} = \{(x, e) \mid x \in S_1\}$ ,  $\overline{S_2} = \{(t, z) \mid t \in S_1, z \in S_2\}$  and  $\Gamma = \text{Cay}(G, S)$ . If  $G = G_1 \times G_2$  and  $S = \overline{S_1} \cup \overline{S_2}$  then  $\Gamma \cong \Gamma_1 \nabla \Gamma_2$ .*

*Proof.* By the definition of converse skew product of graphs,  $V(\Gamma) = V(\Gamma_1 \nabla \Gamma_2) = V(\Gamma_1) \times V(\Gamma_2)$ . On the other hand,

$$\begin{aligned}
 E(\Gamma) &= \left\{ (a, b)(c, d) \mid (a, b)(c^{-1}, d^{-1}) \in S \right\} \\
 &= \left\{ (a, b)(c, d) \mid (ac^{-1}, bd^{-1}) \in S \right\} \\
 &= \left\{ (a, b)(c, d) \mid (ac^{-1}, bd^{-1}) \in \overline{S_1} \vee (ac^{-1}, bd^{-1}) \in \overline{S_2} \right\} \\
 &= \left\{ (a, b)(c, d) \mid (ac^{-1} \in S_1 \wedge bd^{-1} = e) \vee (ac^{-1} \in S_1 \wedge bd^{-1} \in S_2) \right\} \\
 &= \left\{ (a, b)(c, d) \mid (ac \in E(\Gamma_1) \wedge b = d) \vee (ac \in E(\Gamma_1) \wedge bd \in E(\Gamma_2)) \right\} \\
 &= E(\Gamma_1 \nabla \Gamma_2).
 \end{aligned}$$

Thus,  $\Gamma = \Gamma_1 \nabla \Gamma_2$ , which completes our argument.  $\square$

Notice that the set  $S$  in Proposition 2.8 is not uniquely determined. To see this, we assume that  $K_4$  denotes the Klein four-group generated by  $a$  and  $b$ . Then

$$\text{Cay}\left(V_4 \times \mathbb{Z}_2, \{(a, 1), (e, 1), (b, 0), (c, 0)\}\right) \cong \text{Cay}(V_4, \{a, b\}) \nabla \text{Cay}(\mathbb{Z}_2, \{1\}),$$

and  $\{(a, 1), (b, 1), (a, 0), (b, 0)\} \neq \{(a, 1), (e, 1), (b, 0), (c, 0)\}$ .

Suppose that  $\Gamma_1, \Gamma_2, \dots, \Gamma_n$  is a sequence of graphs. The converse skew product

$$\Gamma_1 \nabla \left( \Gamma_2 \nabla \left( \Gamma_3 \nabla \left( \dots \nabla (\Gamma_{n-1} \nabla \Gamma_n) \dots \right) \right) \right),$$

has  $\{(x_1, x_2, \dots, x_n) \mid x_i \in V(\Gamma_i); 1 \leq i \leq n\}$  as vertex set, and two vertices  $(x_1, x_2, \dots, x_n)$  and  $(y_1, y_2, \dots, y_n)$  are adjacent if and only if there exists  $m$ ,  $1 \leq m \leq n$ , such that for each  $i$ ,  $1 \leq i \leq m-1$ ,  $x_i y_i \in E(\Gamma_i)$  and for each  $j$ ,  $m \leq j \leq n$ ,  $x_j = y_j$ .

**Corollary 2.9.** *Let  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\dots$ ,  $\Gamma_n = \text{Cay}(G_n, S_n)$  and  $\Gamma = \text{Cay}(G, S)$ , where  $G = G_1 \times G_2 \times \dots \times G_n$ . Define:*

$$\begin{aligned} \overline{S_1} &= \{(x_1, e, \dots, e) \mid x_1 \in S_1\}, \\ \overline{S_2} &= \{(x_1, x_2, e, \dots, e) \mid x_1 \in S_1 \wedge x_2 \in S_2\}, \\ &\vdots \\ \overline{S_{n-1}} &= \{(x_1, x_2, \dots, x_{n-1}, e) \mid x_i \in S_i; 1 \leq i \leq n-1\}, \\ \overline{S_n} &= \{(x_1, x_2, \dots, x_{n-1}, x_n) \mid x_i \in S_i; 1 \leq i \leq n\}, \\ S &= \overline{S_1} \cup \overline{S_2} \cup \dots \cup \overline{S_n}. \end{aligned}$$

Then,  $\Gamma \cong \Gamma_1 \nabla \left( \Gamma_2 \nabla \left( \Gamma_3 \nabla \left( \dots \nabla (\Gamma_{n-1} \nabla \Gamma_n) \dots \right) \right) \right)$ .

*Proof.* By the definition,  $V(\Gamma) = \left( \Gamma_1 \nabla \left( \Gamma_2 \nabla \left( \dots \nabla (\Gamma_{n-1} \nabla \Gamma_n) \dots \right) \right) \right) = V(\Gamma_1) \times \dots \times V(\Gamma_n)$ . On the other hand,

$$\begin{aligned} E(\Gamma) &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1 b_1^{-1}, a_2 b_2^{-1}, \dots, a_n b_n^{-1}) \in S \right\} \\ &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1 b_1^{-1}, a_2 b_2^{-1}, \dots, a_n b_n^{-1}) \in \overline{S_1} \right. \\ &\quad \left. \vee (a_1 b_1^{-1}, a_2 b_2^{-1}, \dots, a_n b_n^{-1}) \in \overline{S_2} \vee \dots \vee (a_1 b_1^{-1}, a_2 b_2^{-1}, \dots, a_n b_n^{-1}) \in \overline{S_n} \right\} \\ &= \left\{ (a_1, \dots, a_n)(b_1, \dots, b_n) \mid (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} = e \wedge \dots \wedge a_n b_n^{-1} = e) \right. \\ &\quad \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} \in S_2 \wedge a_3 b_3^{-1} = e \wedge \dots \wedge a_n b_n^{-1} = e) \\ &\quad \vee \dots \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} \in S_2 \wedge \dots \wedge a_{n-1} b_{n-1}^{-1} \in S_{n-1} \wedge a_n b_n^{-1} = e) \\ &\quad \left. \vee (a_1 b_1^{-1} \in S_1 \wedge \dots \wedge a_{n-1} b_{n-1}^{-1} \in S_{n-1} \wedge a_n b_n^{-1} \in S_n) \right\}. \end{aligned}$$

So,



$$\begin{aligned}
E(\Gamma) &= \left\{ (a_1, \dots, a_n)(b_1, \dots, b_n) \mid (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge \dots \wedge a_n = b_n) \right. \\
&\vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge \dots \wedge a_n = b_n) \\
&\vee \dots \vee (a_1b_1 \in E(\Gamma_1) \wedge \dots \wedge a_{n-1}b_{n-1} \in E(\Gamma_{n-1}) \wedge a_n = b_n) \\
&\vee \left. (a_1b_1 \in E(\Gamma_1) \wedge \dots \wedge a_{n-1}b_{n-1} \in E(\Gamma_{n-1}) \wedge a_nb_n \in E(\Gamma_n)) \right\} \\
&= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge \dots \right. \\
&\wedge a_n = b_n) \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge \dots \wedge a_n = b_n) \\
&\vee \dots \\
&\vee \left( (a_1b_1 \in E(\Gamma_1) \wedge \dots \wedge a_{n-2}b_{n-2} \in E(\Gamma_{n-2})) \right. \\
&\wedge \left. \left( (a_{n-1}b_{n-1} \in E(\Gamma_{n-1}) \wedge a_n = b_n) \right) \right) \\
&\vee \left. \left( (a_{n-1}b_{n-1} \in E(\Gamma_{n-1}) \wedge a_nb_n \in E(\Gamma_n)) \right) \right\} \\
&= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge \dots \right. \\
&\wedge a_n = b_n) \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge \dots \wedge a_n = b_n) \\
&\vee \dots \vee (a_1b_1 \in E(\Gamma_1) \wedge \dots \wedge a_{n-2}b_{n-2} \in E(\Gamma_{n-2}) \wedge a_{n-1} = b_{n-1} \wedge a_n = b_n) \\
&\vee (a_1b_1 \in E(\Gamma_1) \wedge \dots \wedge a_{n-2}b_{n-2} \in E(\Gamma_{n-2}) \\
&\wedge (a_{n-1}, a_n)(b_{n-1}, b_n) \in E(\Gamma_{n-1} \nabla \Gamma_n)) \left. \right\} \\
&= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge \dots \right. \\
&\wedge a_n = b_n) \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge \dots \wedge a_n = b_n) \\
&\vee \dots \\
&\vee \left( (a_1b_1 \in E(\Gamma_1) \wedge \dots \wedge a_{n-3}b_{n-3} \in E(\Gamma_{n-3})) \right. \\
&\wedge \left. \left( (a_{n-2}b_{n-2} \in E(\Gamma_{n-2}) \wedge a_{n-1} = b_{n-1} \wedge a_n = b_n) \right) \right) \\
&\vee \left. \left( (a_{n-2}b_{n-2} \in E(\Gamma_{n-2}) \wedge (a_{n-1}, a_n)(b_{n-1}, b_n) \in E(\Gamma_{n-1} \nabla \Gamma_n)) \right) \right\} \\
&= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge \dots \right. \\
&\wedge a_n = b_n) \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge \dots \wedge a_n = b_n) \\
&\vee \dots \\
&\vee \left( (a_1b_1 \in E(\Gamma_1) \wedge \dots \wedge a_{n-3}b_{n-3} \in E(\Gamma_{n-3}) \right. \\
&\wedge \left. (a_{n-2}, a_{n-1}, a_n)(b_{n-2}, b_{n-1}, b_n) \in E(\Gamma_{n-2} \nabla (\Gamma_{n-1} \nabla \Gamma_n)) \right) \left. \right\} \\
&= \dots
\end{aligned}$$

Therefore,

$$\begin{aligned}
E(\Gamma) &= \left\{ (a_1, a_2, \dots, a_n)(b_1, b_2, \dots, b_n) \mid (a_1 b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge \dots \right. \\
&\quad \left. \wedge a_n = b_n) \vee \left( a_1 b_1 \in E(\Gamma_1) \wedge (a_2, \dots, a_n)(b_2, \dots, b_n) \right. \right. \\
&\quad \left. \left. \in E\left(\Gamma_2 \nabla \left(\Gamma_3 \nabla \left(\Gamma_4 \nabla (\dots \nabla (\Gamma_{n-1} \nabla \Gamma_n) \dots)\right)\right)\right)\right) \right\} \\
&= E\left(\Gamma_1 \nabla \left(\Gamma_2 \nabla \left(\Gamma_3 \nabla (\dots \nabla (\Gamma_{n-1} \nabla \Gamma_n) \dots)\right)\right)\right).
\end{aligned}$$

which implies that  $\Gamma = \Gamma_1 \nabla \left(\Gamma_2 \nabla \left(\Gamma_3 \nabla (\dots \nabla (\Gamma_{n-1} \nabla \Gamma_n) \dots)\right)\right)$ .  $\square$

We can define the converse skew product of  $n$  graphs  $\Gamma_1, \Gamma_2, \dots, \Gamma_n$  by

$$\left( \dots \left( (\Gamma_1 \nabla \Gamma_2) \nabla \Gamma_3 \right) \nabla \dots \right) \nabla \Gamma_n.$$

Then the vertex set will be again  $V(\Gamma_1) \times \dots \times V(\Gamma_n)$  and two vertices

$$(x_1, x_2, \dots, x_n) \text{ and } (y_1, y_2, \dots, y_n)$$

are adjacent if and only if  $x_1 y_1 \in E(\Gamma_1)$  and for each  $i$ ,  $2 \leq i \leq n$ ,  $x_i = y_i$  or  $x_i y_i \in E(\Gamma_i)$ .

**Corollary 2.10.** *Suppose  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\dots$ ,  $\Gamma_n = \text{Cay}(G_n, S_n)$  and  $\Gamma = \text{Cay}(G, S)$ , where  $G = G_1 \times G_2 \times \dots \times G_n$  and*

$$S = \{(x_1, x_2, \dots, x_n) \mid x_1 \in S_1, \forall 2 \leq i \leq n : x_i \in S_i \vee x_i = e\}.$$

Then  $\Gamma = \left( \dots \left( (\Gamma_1 \nabla \Gamma_2) \nabla \Gamma_3 \right) \nabla \dots \right) \nabla \Gamma_n$ .

*Proof.* The proof in general case is tedious and so similar to Corollary 2.7. We will prove the result for  $n = 4$ . We first notice that

$$V(\Gamma) = V\left(\left(\left(\Gamma_1 \nabla \Gamma_2\right) \nabla \Gamma_3\right) \nabla \Gamma_4\right) = (\Gamma_1) \times V(\Gamma_2) \times V(\Gamma_3) \times V(\Gamma_4).$$

So, it is enough to prove the equality of edge sets.

$$\begin{aligned}
E(\Gamma) &= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid (a_1 b_1^{-1}, a_2 b_2^{-1}, a_3 b_3^{-1}, a_4 b_4^{-1}) \in S \right\} \\
&= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} = e \wedge a_3 b_3^{-1} = e \wedge a_4 b_4^{-1} = e) \right. \\
&\quad \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} \in S_2 \wedge a_3 b_3^{-1} = e \wedge a_4 b_4^{-1} = e) \\
&\quad \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} = e \wedge a_3 b_3^{-1} \in S_3 \wedge a_4 b_4^{-1} = e) \\
&\quad \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} = e \wedge a_3 b_3^{-1} = e \wedge a_4 b_4^{-1} \in S_4) \\
&\quad \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} \in S_2 \wedge a_3 b_3^{-1} \in S_3 \wedge a_4 b_4^{-1} = e) \\
&\quad \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} \in S_2 \wedge a_3 b_3^{-1} = e \wedge a_4 b_4^{-1} \in S_4) \\
&\quad \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} = e \wedge a_3 b_3^{-1} \in S_3 \wedge a_4 b_4^{-1} \in S_4) \\
&\quad \left. \vee (a_1 b_1^{-1} \in S_1 \wedge a_2 b_2^{-1} \in S_2 \wedge a_3 b_3^{-1} \in S_3 \wedge a_4 b_4^{-1} \in S_4) \right\}.
\end{aligned}$$

So,

$$\begin{aligned}
E(\Gamma) &= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge a_3 = b_3 \right. \\
&\quad \wedge a_4 = b_4) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge a_4 = b_4) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4 = b_4) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4 = b_4) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2 \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \left. \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \right\} \\
&= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \left( (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2) \right. \right. \\
&\quad \left. \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2)) \right) \wedge (a_3 = b_3 \wedge a_4 = b_4) \\
&\quad \vee \left( (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2) \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2)) \right) \\
&\quad \wedge (a_3b_3 \in E(\Gamma_3) \wedge a_4 = b_4) \\
&\quad \vee \left( (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2) \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2)) \right) \\
&\quad \wedge (a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4)) \\
&\quad \vee \left( (a_1b_1 \in E(\Gamma_1) \wedge a_2 = b_2) \vee (a_1b_1 \in E(\Gamma_1) \wedge a_2b_2 \in E(\Gamma_2)) \right) \\
&\quad \left. \wedge (a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4)) \right\} \\
&= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3 = b_3 \right. \right. \\
&\quad \left. \wedge a_4 = b_4 \right) \vee \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4 = b_4 \right) \\
&\quad \vee \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3 = b_3 \wedge a_4b_4 \in E(\Gamma_4) \right) \\
&\quad \left. \vee \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \wedge a_4b_4 \in E(\Gamma_4) \right) \right\} \\
&= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \left( \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3 = b_3 \right) \right. \right. \\
&\quad \vee \left. \left. \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \right) \right) \right. \\
&\quad \left. \wedge a_4 = b_4 \right) \vee \left( \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3 = b_3 \right) \right. \\
&\quad \left. \vee \left( (a_1, a_2)(b_1, b_2) \in E(\Gamma_1 \nabla \Gamma_2) \wedge a_3b_3 \in E(\Gamma_3) \right) \right) \wedge a_4b_4 \in E(\Gamma_4) \left. \right\}.
\end{aligned}$$

Therefore, we have:

$$\begin{aligned} E(\Gamma) &= \left\{ (a_1, a_2, a_3, a_4)(b_1, b_2, b_3, b_4) \mid \left( (a_1, a_2, a_3)(b_1, b_2, b_3) \in E((\Gamma_1 \nabla \Gamma_2) \nabla \Gamma_3) \right. \right. \\ &\quad \left. \left. \wedge a_4 = b_4 \right) \vee \left( (a_1, a_2, a_3)(b_1, b_2, b_3) \in E((\Gamma_1 \nabla \Gamma_2) \nabla \Gamma_3) \wedge a_4 b_4 \in E(\Gamma_4) \right) \right\} \\ &= E\left( ((\Gamma_1 \nabla \Gamma_2) \nabla \Gamma_3) \nabla \Gamma_4 \right), \end{aligned}$$

which completes our argument.  $\square$

If  $B = \{(1, 0), (0, 1)\}$  then the NEPS of graphs  $\Gamma_1$  and  $\Gamma_2$  is just its Cartesian product of these graphs. The Cartesian product of Cayley graphs were considered in [1, Lemma 2.6]. The case of  $B = \{(1, 1)\}$  leads to the tensor product of graphs. The tensor product of Cayley graphs were studied in [6, Proposition 2.1]. So, it is natural to consider the general case of the NPES of Cayley graphs.

**Proposition 2.11.** *Suppose  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\Gamma = \text{Cay}(G, S)$  and  $B = \{(1, 0)\}$ , where  $G = G_1 \times G_2$  and  $S = \{(x, e) \mid x \in S_1\}$ . Then  $\Gamma = \Gamma_1 \text{ NEPS } \Gamma_2$ .*

*Proof.* By the definition  $V(\Gamma) = V(\Gamma_1 \text{ NEPS } \Gamma_2) = V(\Gamma_1) \times V(\Gamma_2)$ . On the other hand,

$$\begin{aligned} E(\Gamma) &= \{(x_1, x_2)(y_1, y_2) \mid (x_1, x_2)(y_1^{-1}, y_2^{-1}) \in S\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid (x_1 y_1^{-1}, x_2 y_2^{-1}) \in S\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid x_1 y_1^{-1} \in S_1 \wedge x_2 y_2^{-1} = e\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid x_1 y_1 \in E(\Gamma_1) \wedge x_2 = y_2\} \\ &= E(\Gamma_1 \text{ NEPS } \Gamma_2). \end{aligned}$$

Hence  $\Gamma = \Gamma_1 \text{ NEPS } \Gamma_2$ , so desired.  $\square$

**Proposition 2.12.** *Suppose  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\Gamma = \text{Cay}(G, S)$  and  $B = \{(0, 1)\}$ , where  $G = G_1 \times G_2$  and  $S = \{(e, y) \mid y \in S_2\}$ . Then  $\Gamma = \Gamma_1 \text{ NEPS } \Gamma_2$ .*

*Proof.* By the definition  $V(\Gamma) = V(\Gamma_1 \text{ NEPS } \Gamma_2) = V(\Gamma_1) \times V(\Gamma_2)$ . On the other hand,

$$\begin{aligned} E(\Gamma) &= \{(x_1, x_2)(y_1, y_2) \mid (x_1, x_2)(y_1^{-1}, y_2^{-1}) \in S\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid (x_1 y_1^{-1}, x_2 y_2^{-1}) \in S\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid x_1 y_1^{-1} = e \wedge x_2 y_2^{-1} \in S_2\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid x_1 = y_1 \wedge x_2 y_2 \in E(\Gamma_2)\} \\ &= E(\Gamma_1 \text{ NEPS } \Gamma_2). \end{aligned}$$

Therefore,  $\Gamma = \Gamma_1 \text{ NEPS } \Gamma_2$ , which completes our argument.  $\square$

**Proposition 2.13.** *Suppose  $\Gamma_1 = \text{Cay}(G_1, S_1)$ ,  $\Gamma_2 = \text{Cay}(G_2, S_2)$ ,  $\Gamma = \text{Cay}(G, S)$  and  $B = \{(1, 0), (0, 1), (1, 1)\}$ , where  $G = G_1 \times G_2$ ,  $\overline{S}_1 = \{(x, e) \mid x \in S_1\}$ ,  $\overline{S}_2 = \{(e, y) \mid y \in S_2\}$  and  $S = \overline{S}_1 \cup \overline{S}_2 \cup S_1 \times S_2$ . Then  $\Gamma = \Gamma_1 \text{ NEPS } \Gamma_2 = \Gamma_1 \boxtimes \Gamma_2$ .*

*Proof.* By the definition of NEPS and Strong product of graphs

$$V(\Gamma) = V(\Gamma_1 NEPS \Gamma_2) = V(\Gamma_1 \boxtimes \Gamma_2) = V(\Gamma_1) \times V(\Gamma_2).$$

On the other hand,

$$\begin{aligned} E(\Gamma) &= \{(x_1, x_2)(y_1, y_2) \mid (x_1, x_2)(y_1^{-1}, y_2^{-1}) \in S\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid (x_1 y_1^{-1}, x_2 y_2^{-1}) \in S\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid (x_1 y_1^{-1} \in S_1 \wedge x_2 y_2^{-1} = e) \\ &\vee (x_1 y_1^{-1} \in S_1 \wedge x_2 y_2^{-1} = e) \vee (x_1 y_1^{-1} \in S_1 \wedge x_2 y_2^{-1} \in S_2)\} \\ &= \{(x_1, x_2)(y_1, y_2) \mid (x_1 y_1 = e \wedge x_2 y_2 \in E(\Gamma_2)) \\ &\vee (x_1 y_1 \in E(\Gamma_1) \wedge x_2 = y_2) \vee (x_1 y_1 \in E(\Gamma_1) \wedge x_2 y_2 \in E(\Gamma_2))\} \\ &= E(\Gamma_1 NEPS \Gamma_2) = E(\Gamma_1 \boxtimes \Gamma_2). \end{aligned}$$

Thus,  $\Gamma = \Gamma_1 NEPS \Gamma_2$ . □

### 3. CONCLUDING REMARKS

In an earlier paper the present authors [6] investigated the behavior of Cayley graphs under graph operations: tensor product, composition, symmetric difference, disjunction and splice of Cayley graphs. In this paper, we consider some new operations containing *NEPS*, corona, hierarchical, strong, skew and converse skew product of Cayley graphs. Some conditions are obtained such that the Cayley graphs under these graph operations are again Cayley graphs.

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