



ON THE NORM OF JORDAN *-DERIVATIONS

ABOLFAZL NIAZI MOTLAGH

Communicated by M. Ito

ABSTRACT. Let \mathcal{H} be a complex Hilbert space and let $B(\mathcal{H})$ be the algebra of all bounded linear operators on \mathcal{H} . Let $T \in B(\mathcal{H})$. In this paper, we determine the norm of the inner Jordan *-derivation $\Delta_T : X \mapsto TX - X^*T$ acting on the Banach algebra $B(\mathcal{H})$. More precisely, we show that

$$\|\Delta_T\| \geq 2 \sup_{\lambda \in W_0(T)} |\operatorname{Im}(\lambda)|$$

in which $W_0(T)$ is the maximal numerical range of operator T .

1. INTRODUCTION AND PRELIMINARIES

Let \mathfrak{A} be a *-algebra. A Jordan *-derivation on \mathfrak{A} is a linear mapping $E : \mathfrak{A} \rightarrow \mathfrak{A}$ which satisfies

$$E(a^2) = aE(a) + E(a)a^*$$

for all $a \in \mathfrak{A}$. Note that for a fixed $a \in \mathfrak{A}$ the mapping $\Delta_a(x) = ax - x^*a$ is a Jordan *-derivation; such a Jordan *-derivation is said to be inner.

In [1, 4], we can see the following results:

- (1) Every Jordan *-derivation on complex *-algebra with identity is inner.
- (2) Every Jordan *-derivation on the algebra of all bounded linear operators on a real Hilbert space \mathcal{H} with $\dim \mathcal{H} > 1$, is inner.
- (3) Every Jordan *-derivation on the quaternion algebra is inner.

Let \mathcal{H} be a complex infinite dimensional Hilbert space and let $B(\mathcal{H})$ be the Banach algebra of all bounded linear operators on \mathcal{H} . For operators $A, B \in B(\mathcal{H})$, we define the generalized Jordan *-derivation $\Delta_{A,B}$ by

$$\Delta_{A,B}(X) = AX - X^*B$$

Date: Received: 21 January 2019; Revised: 8 April 2019; Accepted: 9 April 2019.

2010 Mathematics Subject Classification. Primary 47A20; Secondary 47B47.

Key words and phrases. Jordan*-derivation, numerical range, maximal numerical range.

for all $X \in B(\mathcal{H})$. Note that if $A = B$, then $\Delta_{A,A} = \Delta_A$ is a Jordan *-derivation.

The notion of numerical range (also called field of values) was firstly introduced by O. Toeplitz [6] in 1918 for matrices, but his definition applies equally well to operators on infinite dimensional Hilbert spaces.

The numerical range of $A \in B(\mathcal{H})$ is defined by $W(A) = \{\langle Ax, x \rangle : x \in \mathcal{H}, \|x\| = 1\}$ and the numerical radius of A is defined by $w(A) = \sup\{|\lambda| : \lambda \in W(A)\}$ where $\langle \cdot, \cdot \rangle$ and $\|\cdot\|$ stand, respectively, for the scalar product on \mathcal{H} and the norm associated with it. In [3], it was shown that $\overline{W(A)}$ is a compact convex subset of \mathbb{C} and that $\sigma(A) \subseteq \overline{W(A)}$, where $\sigma(A)$, the spectrum of A , consists of those complex numbers λ such that $A - \lambda I$ is not invertible. The spectral radius is given by $r(A) = \sup\{|\lambda| : \lambda \in \sigma(A)\}$. The relation between the numerical range and the spectrum of an operator has been studied by several mathematicians; see, for instance, [2, 3].

The concept of maximal numerical range was introduced by Stampfli [5] for proving the norm of a derivation.

Definition 1.1. Let A be a bounded linear operator on a complex Hilbert space \mathcal{H} . The maximal numerical range of A is defined to be the set

$$W_0(A) = \{\lambda \in \mathbb{C} : \langle Ax_n, x_n \rangle \rightarrow \lambda, \text{ where } \|x_n\| = 1 \text{ and } \|Ax_n\| \rightarrow \|A\|\}.$$

It was shown in [5, Lemma 2] that $W_0(A)$ is convex and is contained in the closure of $W(A)$.

In the next section, we investigate the norm of an inner Jordan *-derivation $\Delta_T : X \mapsto TX - X^*T$ acting on $B(\mathcal{H})$. We show that

$$\begin{aligned} &\text{If } \lambda \in W_0(T), \text{ then } \|\Delta_T\| \geq 2(\|T\|^2 - |\lambda|^2)^{\frac{1}{2}}. \\ &\|\Delta_T\| \geq 2 \sup_{\lambda \in W_0(T)} |\operatorname{Im}(\lambda)|. \\ &\|\Delta_T\| = 2\|T\| \text{ if and only if } 0 \in W_0(T). \\ &\text{If } i\|T\| \in W_0(T), \text{ then } \|\Delta_T\| = 2\|T\|. \end{aligned}$$

2. MAIN RESULTS

Using some techniques from [5], we have the following result.

Theorem 2.1. *Let \mathcal{H} be a Hilbert space and let $T \in B(\mathcal{H})$. If $\lambda \in W_0(T)$, then $\|\Delta_T\| \geq 2(\|T\|^2 - |\lambda|^2)^{\frac{1}{2}}$.*

Proof. Suppose that $\lambda \in W_0(T)$. Then there exists a sequence $\{x_n\} \subseteq \mathcal{H}$ such that $\|x_n\| = 1$, $\lim_n \|Tx_n\| = \|T\|$ and $\lim_n \langle Tx_n, x_n \rangle = \lambda$. Set $Tx_n = \alpha_n x_n + \beta_n y_n$ in which $\langle x_n, y_n \rangle = 0$ and $\|y_n\| = 1$ for all $n \in \mathbb{N}$. Hence

$$|\langle Tx_n, x_n \rangle| = |\langle \alpha_n x_n + \beta_n y_n, x_n \rangle| = |\alpha_n| \longrightarrow \lambda.$$

Now for all $n \in \mathbb{N}$ define $V_n : \mathcal{H} \mapsto \mathcal{H}$ by $V_n(x_n) = x_n, V_n(y_n) = -y_n$ and $V_n \Big|_{\text{span}\{x_n, y_n\}^\perp} = 0$. It is easy to see that $V_n^* = V_n$ and

$$\begin{aligned} \|\Delta_T(V_n)(x_n)\| &= \|(TV_n - V_n^*T)(x_n)\| \\ &= \|Tx_n - V_n^*(\alpha_n x_n + \beta_n y_n)\| \\ &= \|\alpha_n x_n + \beta_n y_n - \alpha_n x_n + \beta_n y_n\| \\ &= 2|\beta_n|. \end{aligned}$$

Since $0 \leq \lim_n (\|T\|^2 - \|Tx_n\|^2) = \lim_n (\|T\|^2 - |\alpha_n|^2 - |\beta_n|^2) = 0$, there exists a sequence $\{\varepsilon_n\} \subseteq \mathbb{R}^+$ such that $\varepsilon_n \rightarrow 0$ and $0 \leq (\|T\|^2 - |\alpha_n|^2)^{\frac{1}{2}} - |\beta_n| \leq \frac{1}{2}\varepsilon_n$. Using $|\alpha_n| \rightarrow \lambda$ and $\|\Delta_T(V_n)(x_n)\| = 2|\beta_n| \geq 2(\|T\|^2 - |\alpha_n|^2)^{\frac{1}{2}} - \varepsilon_n$ implies that $\|\Delta_T\| \geq 2(\|T\|^2 - |\lambda|^2)^{\frac{1}{2}}$. \square

Now, The following corollary shows the relation between the norm of Δ_T and the maximal numerical range.

Corollary 2.2. *Let \mathcal{H} be a Hilbert space and let $T \in B(\mathcal{H})$. Then $\|\Delta_T\| = 2\|T\|$ if and only if $0 \in W_0(T)$.*

Proof. Let $0 \in W_0(T)$. By Theorem (2.1), we can conclude that $\|\Delta_T\| \geq 2\|T\|$ and that the upper estimate $\|\Delta_T\| \leq 2\|T\|$ is trivial, so $\|\Delta_T\| = 2\|T\|$.

Now, let $\|\Delta_T\| = 2\|T\|$. Then there exist sequences $\{x_n\} \subseteq \mathcal{H}$ and $A_n \subseteq B(\mathcal{H})$ such that $\|x_n\| = \|A_n\| = 1$ and $\|\Delta_T(A_n)(x_n)\| \rightarrow 2\|T\|$. Since $\lim_n \|A_n x_n\| = 1$, we have $\lim_n \|Tx_n\| = \|T\|$ and $\lim_n \|TA_n x_n\| = \|T\|$, $\lim_n \|A_n^* x_n\| = 1$.

Set $y_n = TA_n x_n + A_n^* T x_n$. Using the $\lim_n \|\Delta_T(A_n)(x_n)\| = 2\|T\|$ implies that $\lim_n \|y_n\| = 0$. Since T is a bounded operator, there exists a subsequence $\{x_{n_k}\}$ such that $\langle Tx_{n_k}, x_{n_k} \rangle$ is a convergence sequence. Therefore, without loss of generality, one can assume that $\lim_n \langle Tx_n, x_n \rangle = \lambda$; hence $\lambda \in W_0(T)$. On the other hand, $\lim_n \langle TA_n x_n, A_n x_n \rangle = -\lambda$ because

$$\begin{aligned} \langle TA_n x_n, A_n x_n \rangle &= \langle -A_n^* T x_n + y_n, A_n x_n \rangle \\ &= -\langle A_n^* T x_n, A_n x_n \rangle + \langle y_n, A_n x_n \rangle \\ &= -\langle Tx_n, A_n^2 x_n \rangle + \langle y_n, A_n x_n \rangle \\ &= -\langle Tx_n, x_n \rangle + \langle Tx_n, x_n - A_n^2 x_n \rangle + \langle y_n, A_n x_n \rangle. \end{aligned}$$

The equality $\lim_n \|A_n x_n\| = 0$ implies $\lim_n \|x_n - A_n^2 x_n\| = 0$, and so

$$\lim_n \langle Tx_n, x_n - A_n^2 x_n \rangle = 0, \lim_n \langle y_n, A_n x_n \rangle = 0.$$

Hence, $\lim_n \langle TA_n x_n, A_n x_n \rangle = \lim_n -\langle Tx_n, x_n \rangle = -\lambda$, and therefore $-\lambda \in W_0(T)$. Since we have $-\lambda, \lambda \in W_0(T)$ and $W_0(T)$ is convex, $0 = \frac{1}{2}\lambda + \frac{1}{2}(-\lambda) \in W_0(T)$. \square

In the following theorem, we give a lower bound for $\|\Delta_T\|$.

Theorem 2.3. *Let \mathcal{H} be a Hilbert space and let $T \in B(\mathcal{H})$. Then*

$$\|\Delta_T\| \geq 2 \sup_{\lambda \in W_0(T)} |\text{Im}(\lambda)|.$$

Proof. Let $\lambda \in W_0(T)$. Then there exists a sequence $\{x_n\} \subseteq \mathcal{H}$ such that $\|x_n\| = 1$, $\lim_n \|Tx_n\| = \|T\|$ and $\lim_n \langle Tx_n, x_n \rangle = \lambda$. Hence,

$$\begin{aligned} \|\Delta_T(x_n \otimes Tx_n)(x_n)\| &= \|T(x_n \otimes Tx_n)(x_n) - (x_n \otimes Tx_n)^*T(x_n)\| \\ &= \|T(x_n \otimes Tx_n)(x_n) - (Tx_n \otimes x_n)T(x_n)\| \\ &= \|T(\langle x_n, Tx_n \rangle x_n) - \langle Tx_n, x_n \rangle Tx_n\| \\ &= \|\langle x_n, Tx_n \rangle Tx_n - \langle Tx_n, x_n \rangle Tx_n\| \\ &= |\langle x_n, Tx_n \rangle - \langle Tx_n, x_n \rangle| \|Tx_n\|. \end{aligned}$$

But since

$$\|\Delta_T(x_n \otimes Tx_n)(x_n)\| \leq \|T\| \|\Delta_T\|,$$

we have

$$|\langle x_n, Tx_n \rangle - \langle Tx_n, x_n \rangle| \|Tx_n\| \leq \|T\| \|\Delta_T\|.$$

Therefore

$$\begin{aligned} \lim_n |\langle x_n, Tx_n \rangle - \langle Tx_n, x_n \rangle| \|Tx_n\| &\leq \lim_n \|T\| \|\Delta_T\| \\ |\bar{\lambda} - \lambda| \|T\| &\leq \|T\| \|\Delta_T\| \\ |\bar{\lambda} - \lambda| &\leq \|\Delta_T\| \\ 2|\operatorname{Im}(\lambda)| &\leq \|\Delta_T\|. \end{aligned}$$

Then

$$\|\Delta_T\| \geq 2 \sup_{\lambda \in W_0(T)} |\operatorname{Im}(\lambda)|.$$

□

Corollary 2.4. *If $i\|T\| \in W_0(T)$, where $i^2 = -1$, then $\|\Delta_T\| = 2\|T\|$.*

REFERENCES

1. M. Brešar and B. Zalar, *On the structure of Jordan *-derivations*, Colloq. Math. **63** (1992), no. 2, 163–171.
2. K.E. Gustafson and D.K.M. Rao, *Numerical Range: The Field of Values of Linear Operators and Matrices*, Springer-Verlag, New York, 1997.
3. P.R. Halmos, *A Hilbert Space Problem Book*, D. Van Nostrand, Princeton-Toronto-London, 1967.
4. P. Šemrl, *On Jordan *-derivations and an application*, Colloq. Math. **59** (1990) 241–251.
5. J.G. Stampfli, *The norm of a derivation*, Pacific J. Math. **33** (1970) 737–747.
6. O. Toeplitz, *Das algebraische Analogon zu einem Satze von Fejer*, Math. Z. **2** (1918) 187–197.

DEPARTMENT OF MATHEMATICS, FACULTY OF BASIC SCIENCES, UNIVERSITY OF BOJNORD,
P.O. BOX 1339, BOJNORD, IRAN.

E-mail address: a.niazi@ub.ac.ir; niazimotlagh@gmail.com